

Highly AC Voltage Fluctuation-Resistant LED Driver with Sinusoid-Like Reference

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Abstract

A novel converter-free AC LED driver that is highly resistant to the fluctuation of AC voltage is proposed in this study. By removing large passive components, such as the bulky capacitor and the large-value inductor, the integration of the driver circuit is enhanced while the driving current remains stable. The proposed circuit provides LED lamps with a driving current that can follow the sinusoid waveform to obtain a very high power factor (PF) and low total harmonic distortion (THD). The LED input current produced by this driving current is insensitive to fluctuations in the AC voltage. Users will thus not feel that LED lamps are flashing during the fluctuation. Experiment results indicate that the proposed system can obtain PF of 0.999 and THD as low as 3.3% for a five-string 6 W LED load under 220 V at 50 Hz.

Keywords: AC LED, Fluctuation in AC voltage, Sinusoid waveform, power factor (PF), Total harmonic distortion (THD)

I. INTRODUCTION

LED is a photoelectric conversion element with high conversion efficiency. Given the absence of lamp filaments, this pure semiconductor luminous element has a long service life and functions as an environmentally friendly light source. With these advantages, LED has been widely used in various fields, including displays, decorations, backlights, general lighting, and urban landscape lighting [1]-[6].

LED current determines the luminous flux output. Designing a highly reliable and efficient LED driving current is thus very important. AC-DC and DC-DC LED driving circuits [7]-[16] are widely utilized in LED lighting systems. They will also be inevitably applied to AC-DC or DC-DC converters; this condition means that large-value inductors and large electrolytic capacitors will be introduced to LED lighting systems. The lifetime of LED drivers is limited by large electrolytic capacitors. AC LED drivers can directly power LED lamps with an AC source. Given that an AC-DC or DC-DC converter is not required, the size of an LED driver is significantly decreased with high integration and its lifetime is

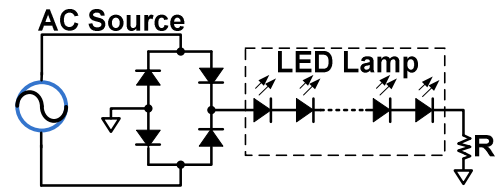


Fig. 1. Bridge AC LED structure.

increased. Two conventional AC LED connection structures exist. One is the inverse-parallel connection of two strings of LED directly connected to the AC source. In the other structure, the AC source directly controls the LED string after the bridge rectifier (Fig. 1) [17]. Although no bulky capacitor is found in the rectifier output, both structures exhibit large current distortion and different high peak currents even under the same input voltage and average input current. An AC LED driving circuit controlled in segments was proposed in [18], [19]. This circuit adopts a segmented driving structure to improve the circuit efficiency effectively, reduce the impact of AC source voltage fluctuation on the circuit, and consequently provide an LED with a stable driving current. However, given the stair-like input LED current, its degree of fitting with the input voltage limits the improvement of the power factor (PF) and total harmonic distribution (THD) of this structure. The driving current provided by a direct AC LED driver in [20] can greatly follow the AC source variation. However, the input current is very sensitive to the AC source fluctuation. Considering the traditional reference voltage generated from a resistor string

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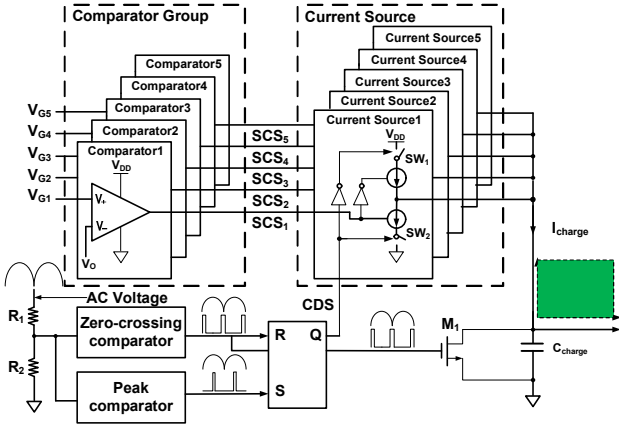


Fig. 3. Structure of the reference voltage generator.

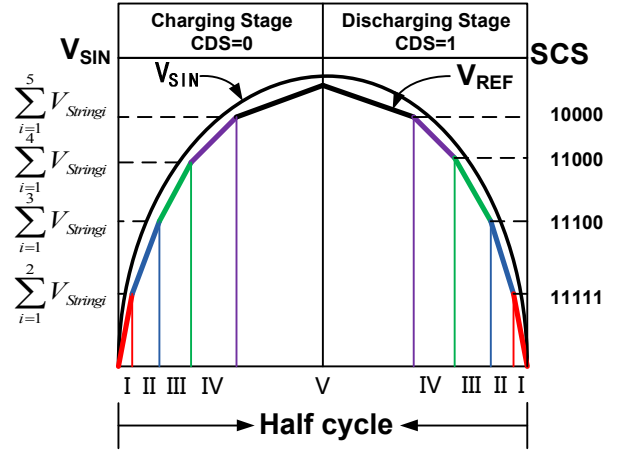
$$I_{LEDn} = V_{REF} / \sum_{i=1}^5 R_{SETn} \quad (1)$$

Considering that V_{REF} is the reference voltage produced by the reference voltage generator that can closely follow V_{SIN} and is not affected by the AC source, the LED driving current composed of every segmented current can properly fit V_{SIN} ; thus, PF and THD are increased. Consequently, users would not feel that LED lamps are flashing when the AC source is unstable.

B. Reference Voltage Generator

As shown in Fig. 3, a novel reference voltage generator was employed in the AC LED driving circuit. The reference voltage (V_{REF}) generated in this structure can well follow the half-sinusoidal waveform. Given that a separated current source exists for the charge and discharge of the capacitor, V_{REF} is insensitive to the tremble of the AC source. The operating principle of this module is discussed in this study.

The input terminals of the zero-crossing and peak comparators are simultaneously connected to the AC line voltage that has been divided by $R1$ and $R2$. The outputs of the zero-crossing and peak comparators are connected to two input terminals of the SR trigger. The output of the SR trigger is connected to selective switches SW_1 and SW_2 as the charge and discharge signal (CDS) of the current source. The zero-crossing comparator produces a transient high pulse when V_{SIN} is zero. Before V_{SIN} increases to the maximum value from zero, the peak comparator and SR trigger outputs remain low. SW_1 is then turned on and SW_2 is turned off. The source current provides the charging current for the capacitor of C_{Charge} , and the capacitor voltage gradually increases from zero. The outputs of the five OPAs (i.e., V_{G1} , V_{G2} , V_{G3} , and V_{G4}) turns from high to level in this order, whereas V_{G5} remains high. After going through the comparator group, these gate voltages generate a group of five bit-segmented control signal

Fig. 4. Illustrative diagram of V_{REF} versus V_{SIN} .

SCS_i ($i = 1, 2, 3, 4, 5$). When SCS_i is high, current source i is connected to the circuit to provide a charging current for the capacitor. Otherwise, the current source is closed. During the process where V_{SIN} increases from zero to the maximum value, SCS decreases from “11111” to “10000.” The total charging current changes along with the change in the V_{SIN} gradient; thus, the output of C_{Charge} closely follows V_{SIN} . When V_{SIN} reaches its maximum value, the peak comparator produces a transient high pulse. The SR trigger generates high voltage accordingly. SW_1 is then turned off and SW_2 is turned on. The current source provides a discharging current for the capacitor C_{Charge} . With the decrease in V_{SIN} , the value of SCS increases and the corresponding discharging current gradually increases. Reset transistor $M1$ prevents the imbalance between charge and discharge of the current source from the voltage shift of the C_{Charge} initial voltage. Therefore, the initial capacitor voltage is zero at the beginning of every cycle.

Fig. 4 is the waveform illustrative diagram of V_{SIN} and V_{REF} derived from AC source after the processing of the bridge rectifier and the reference voltage generator, respectively. We can divide the waveform of the figure into 5 regions. As mentioned before, from regions I to V, CDS is low; C_{Charge} is charging; SCS turns from 11111 to 10000; the total charging current decreases; the corresponding charging voltage gradient also drops. The discharge stage is symmetrical to the charge one. The figure indicates a high fitting degree between the waveform of V_{REF} and that of the V_{SIN} . Considering that the current resource within the chip is directly used to charge the capacitor, V_{REF} is also not sensitive to the AC source fluctuation.

III. SIMULATED AND EXPERIMENTAL RESULTS

A. Simulated Results

The simulation results of the proposed circuit are given in this subsection. The waveform of each part in the reference voltage generator is shown in Fig. 5. Fig. 5(a) demonstrates the waveform of CDS, which controls the charge and discharge of

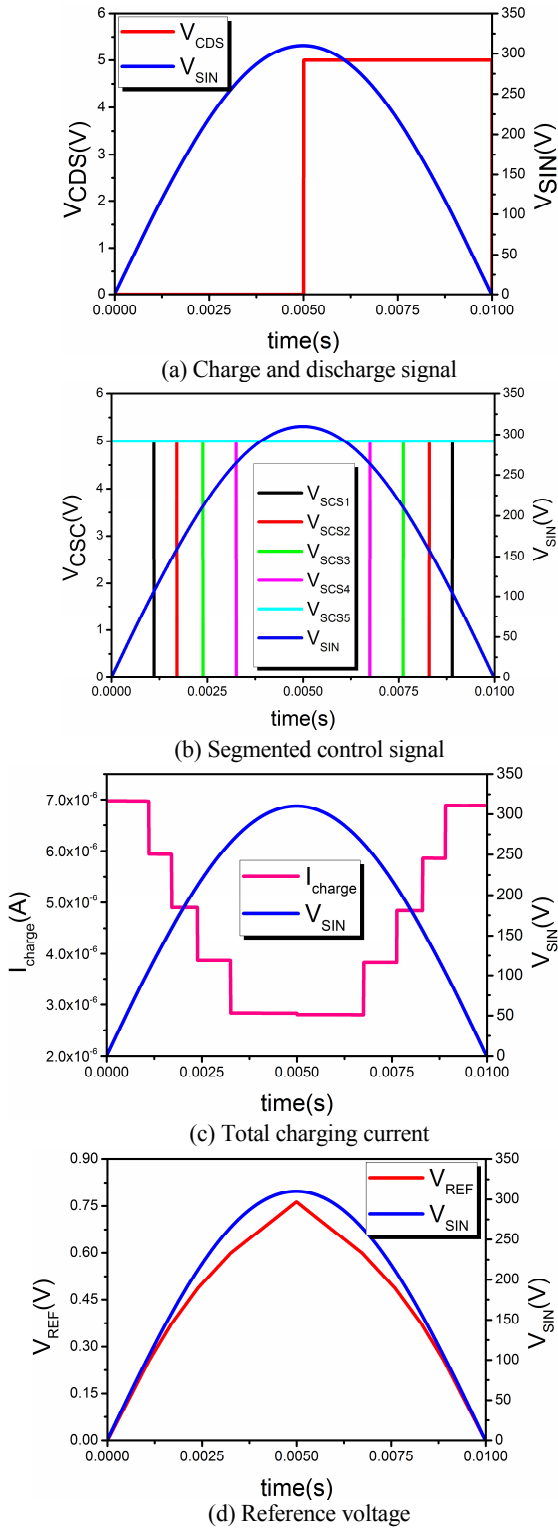


Fig. 5. Simulated results of the reference voltage generator.

the current source. The change in SCS within a half cycle is shown in Fig. 5(b). Fig. 5(c) provides the total charging current, which is symmetrical to the discharging current. Finally, Fig. 5(c) demonstrates V_{REF} , which is the output voltage of the capacitor C_{Charge} . Its voltage waveform greatly follows the half-sinusoid V_{SIN} .

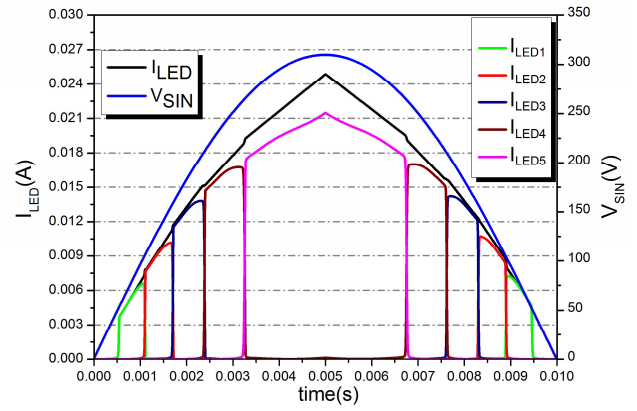


Fig. 6. Simulated I_{LED} versus half-sinusoid V_{SIN} under 220 V at 50 Hz.

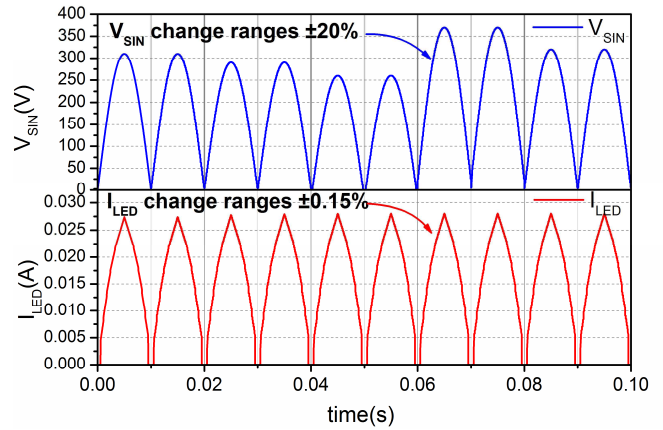


Fig. 7. Simulated I_{LED} versus half-sinusoid V_{SIN} under 220 V at 50 Hz.

The driving current is provided by Drivers 1, 2, 3, 4, and 5 consisting of a five-segment current. The waveform of I_{LED} within the half cycle is shown in Fig. 6. The switching node of every segment current coincides with the charge node of V_{REF} . I_{LED} and V_{SIN} have a high fitting degree. In the simulation, the PF and THD for the five-string 6 W LED load under 220 V at 50 Hz are 0.999 and 3%, respectively. Fig. 7 shows the fluctuation of I_{LED} along V_{SIN} to demonstrate the impact of the AC source on I_{LED} . The maximum value of V_{SIN} is at $\pm 20\%$, whereas the fluctuation in I_{LED} is only at $\pm 0.15\%$. This result indicates that the driving current is insensitive to the AC source fluctuation.

B. Experiment Results

Fig. 8 shows the measurement result of V_{REF} and V_{SIN} after the rectifier bridge under 220 V at 50 Hz. The measurement result shows that V_{REF} is very close to V_{SIN} . Fig. 9 shows the waveform of driving current I_{LED} and input voltage V_{SIN} after the rectifier bridge. The input current fits input voltage V_{SIN} well. The experiment results indicate that the fluctuation in input voltage V_{SIN} is at $\pm 10\%$ and the fluctuation in I_{LED} is at $\pm 0.2\%$. In comparison with the previous structure, the reference

TABLE I
EXPERIMENTS IN DIFFERENT CONDITIONS

Reference Voltage	Number Of Strings	AC Source	Power	PF	THD
Sinusoid-like Reference	1	220 V	6 W	0.979	20.9%
Sinusoid-like Reference	1	110 V	6 W	0.976	23.4%
Sinusoid-like Reference	5	220 V	6 W	0.999	3.3%
Sinusoid-like Reference	5	110 V	6 W	0.997	6.2%
Stair-like Reference	1	220 V	6 W	0.947	33.9%
Stair-like Reference	5	220 V	6 W	0.997	7.2%

TABLE II
PERFORMANCE COMPARED WITH OTHER REFERENCES

References	PF	THD (%)	Efficiency (%)	Number Of Strings	Power (W)
[12]	0.995	8.6	93.4	6	22
[13]	0.997	7.2	90.2	5	19
This study	0.999	3.3	91.6	5	6

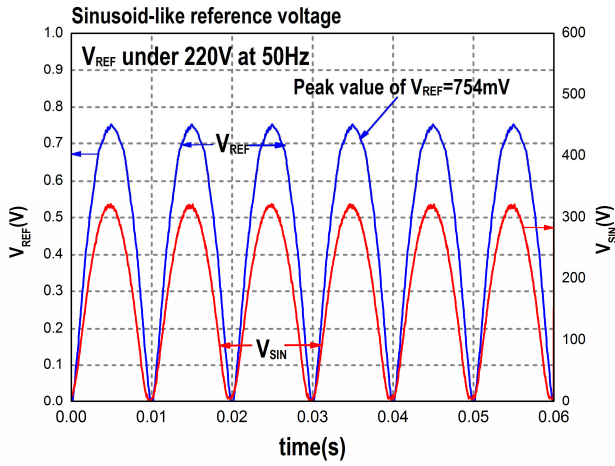


Fig. 8. Measurement result of the sinusoid-like reference voltage under 220 V at 50 Hz.

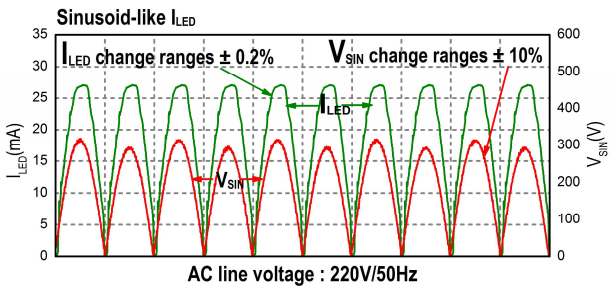


Fig. 9. Measured input voltage and driving current waveform.

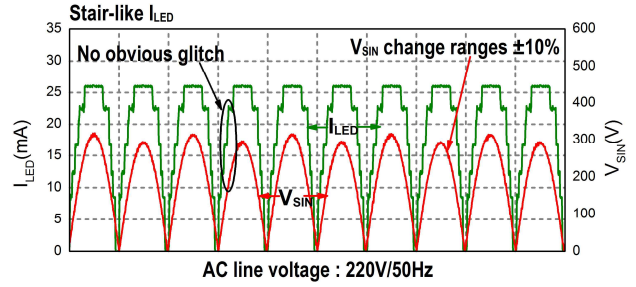


Fig. 10. Measured input voltage and stair-like current waveform.

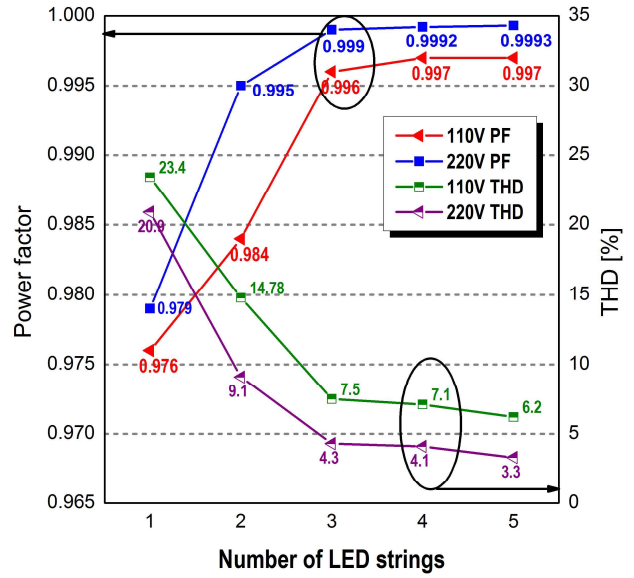


Fig. 11. Power factor and THD versus the number of LED strings. Measurements were conducted at 50 Hz consuming 6 W under different AC supplies.

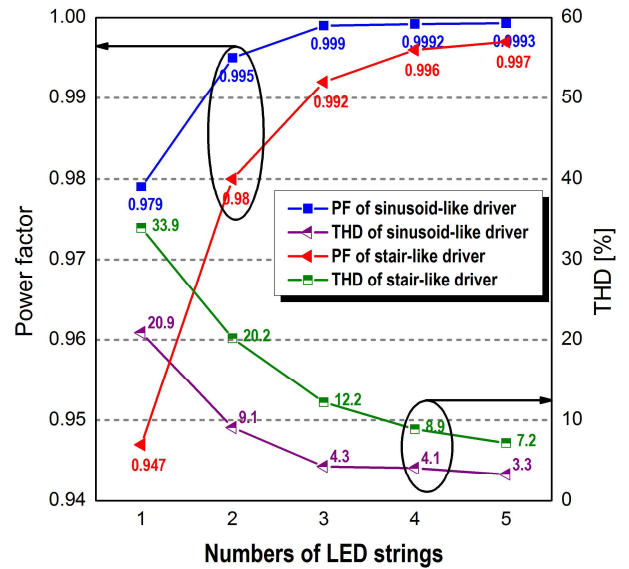


Fig. 12. PF and THD of sinusoid-like and stair-like drivers versus the number of LED strings. Measurements were conducted under 220 V at 50 Hz consuming 6 W.

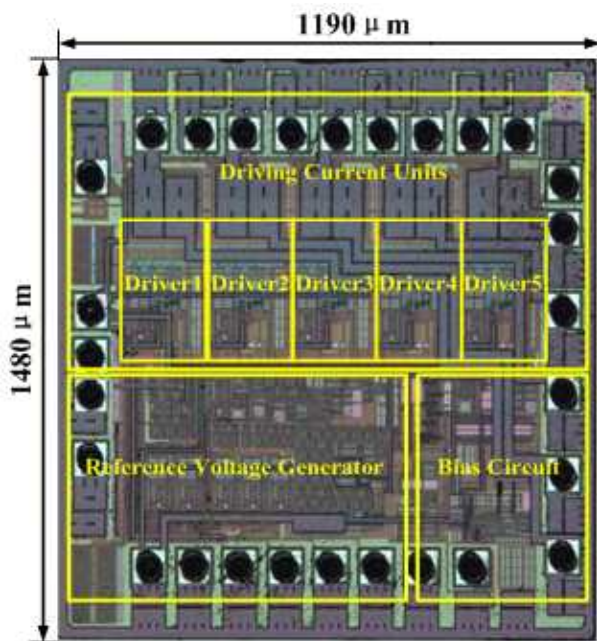


Fig. 13. Micrograph of the fabricated AC LED driver.

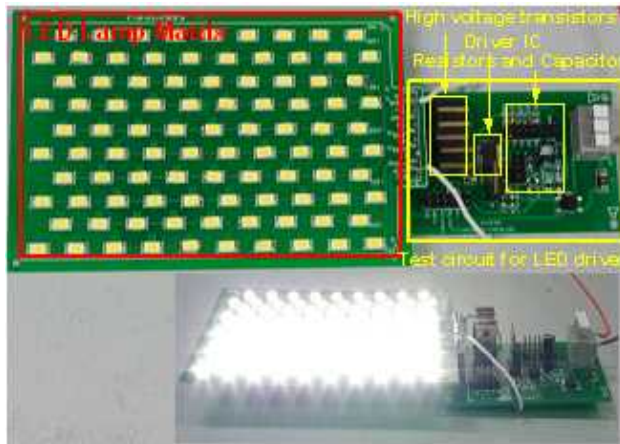


Fig. 14. Photograph of the test circuit with an LED matrix.

of the driving current units was connected to a constant voltage instead of the reference voltage generator. The waveform of the driving current is shown in Fig. 10. The current waveform is in the shape of stairs, and no obvious glitch occurs in the switch between each driving current unit. The measurement results of V_{SIN} , sinusoid-like I_{LED} , and stair-like I_{LED} are obtained under 220 V at 50 Hz consuming 6 W. V_{SIN} changes at $\pm 10\%$. Under the same power, the driving current of 110 V is twice that of 220 V. Fig. 11 shows the PF and THD of the sinusoid-like reference-equipped LED driver with different strings. The driver adopts the proposed sinusoid-like reference voltage generator. The achievable PFs are 0.997 and 0.999 for 110 V at 50 Hz and for 220 V at 50 Hz, respectively, with a five-string 6 W LED load. The THDs are 6.2% and 3.3%, respectively. The PFs and THDs for the sinusoid-like and stair-like drivers

are provided in Fig. 12. The proposed LED driver using a sinusoid-like reference voltage generator obtains high PF and low THD under the same load. Table I shows PF and THD in different conditions. The experiment results at 220 V/50 Hz and 6 W in this study compared with those in other references are summarized in Table II.

Figs. 13 and 14 show the microphotograph of the fabricated IC and test circuit with an LED lamp matrix. The chip was fabricated through 0.25 μm BCD process, and the die area is 1190 $\mu\text{m} \times 1480 \mu\text{m}$. Given the limitations of the process, the six high-voltage transistors are off-chip. Among the six high-voltage transistors, five were used to protect the driving circuit, and one was used to supply power for the chip. The resistors (i.e., R_{SET1} , R_{SET2} , R_{SET3} , R_{SET4} , and R_{SET5}) were implemented outside the chip so that the driving circuit can be adjusted easily. The values of R_{SET1} , R_{SET2} , R_{SET3} , R_{SET4} , and R_{SET5} are 50, 25, 10, 10, and 30 ohms, respectively. Instead of being integrated, the resistors are out-of-chip; therefore, the heating problem of the resistors can be effectively controlled. The charge capacitor was also placed off-chip to obtain a more accurate V_{REF} value.

IV. CONCLUSIONS

An AC LED driver with a sinusoid-like reference and highly resistant to AC voltage fluctuation was developed. The absence of passive components significantly improved the stability and integration of the LED system. The driving circuit of this structure allows the input current of LED to follow the waveform of the input voltage properly; thus, PF is increased and THD is decreased. The driving circuit is also insensitive to AC voltage fluctuation. As a result, users would not feel that LED lamps are flashing during input voltage fluctuation. The proposed driver, with amendments to the peripheral devices, can be applied to 110 and 220 V AC sources and thus has excellent flexibility. This suitability of this driver was demonstrated by a prototype implementation in a 0.25 μm BCD process. The PF and THD of the driving circuit under 6 W/110 V and 6 W/220 V AC voltage reached 0.997/0.999 and 6.2%/3.3%, respectively. The efficiencies are 90.3% and 91.6% for 110 V at 50 Hz and for 220 V at 50 Hz, respectively, with a power consumption of 6 W.

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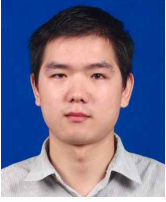
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